

M.A./M.Sc. Semester IV Examination, 2019 (under DDE)

Subject: Mathematics (Applied Stream)

Paper: MAS 403 (Viscous Flows, Boundary Layer Theory and MHD)

Time: 2 Hours

Full Marks: 45

The figures in the margin indicate full marks.

Candidates are required to give their answers in their own words as far as practicable.

[Notation and symbols have their usual meaning]

Answer any **five** questions. Only **first five** answers will be evaluated.

9×5 = 45

- 1 What do you mean by MHD approximations? Find the expression for Lorentz force of a conducting material. Simplify this force using MHD approximations. [3+3+3]
- 2 (a) Establish $\frac{D}{Dt}\left(\frac{\vec{B}}{\rho}\right) = \left(\frac{\vec{B}}{\rho} \cdot \vec{\nabla}\right)\vec{\nabla}$, where symbols have their usual meaning. [6]
(b) Drive Lundquist criterion. [3]
- 3 Describe briefly the Hartman flow in MHD. Find the velocity components of the flow. [4+5]
- 4 State and prove Ferraro's iso-rotation theorem. [2+7]
- 5 What is pinch effect? Discuss linear pinch configuration and its stability behavior. [2+3+4]
- 6 Give the concept of magnetic force-free field. Show that a force-free field is always obtained as a superposition of two different fields which are to be characterized by you? [4+5]
- 7 Briefly discuss MHD Rayleigh problem. Find velocity components when kinematic fluid viscosity \ll magnetic diffusivity. [4+5]

M.A./M.Sc. Semester IV Examination, 2019 (under DDE)

Subject: Mathematics (Pure Stream)

Paper: MPS 403 (Advanced Functional Analysis II)

Time: 2 Hours

Full Marks: 45

The figures in the margin indicate full marks.

Candidates are required to give their answers in their own words as far as practicable.

[Notation and symbols have their usual meaning]

Answer any **five** questions. Only **first five** answers will be evaluated.

9×5 = 45

- 1 Let X be a normed linear space and Y be a subspace of X such that $\text{Dim}(Y) < \infty$. Prove [5+4]

that there exists a best approximation to an element $x \in X$ out of Y . Does the result hold if Y is infinite dimensional? Justify your answer.

- 2 (a) If C is a non-empty closed convex subset of a Hilbert space H , then show that for each $x \in H$ there exists a unique best approximation from C to x . Hence show that C contains a unique vector of smallest norm. [6+3]
- 3 (a) Let B be a Banach algebra with identity e and let $b \in B$. Suppose $\mu \neq 0$ be a complex scalar such that $|\mu| > \|b\|$. Show that $(\mu e - b)^{-1}$ exists and $(\mu e - b)^{-1} = \sum_{k=1}^{\infty} \mu^{-k} b^{k-1} (b^0 = e)$. [5]
- (b) Prove that the collection of all non-invertible elements in a Banach algebra with an identity element is a closed set in it. [4]
- 4 (a) If G be the collection of all invertible elements in a Banach algebra X with an identity element. Prove that the mapping: $G \rightarrow G$ given by $x \rightarrow x^{-1} (x \in G)$ is a homeomorphism. [5]
- (b) Let B be a Banach algebra in which every non-zero element is invertible. Show that B is isometrically isomorphic to the complex field. [4]
- 5 (a) When is a normed linear space said to be reflexive? If X be a reflexive Banach space then prove that every bounded sequence in X^* , the first dual of X has a weakly convergent subsequence. [1+4]
- (b) Find the first conjugate space of \mathbb{R}^n . Is \mathbb{R}^n reflexive? Justify your answer [3+1]
- 6 (a) State and prove Uniform Boundedness Principle and hence show that space \wp of all real valued polynomials $p(s) = \sum_{i=0}^n p_i s^i, s \in \mathbb{R}, p \in \wp$ with norm $\|p\| = \max_{0 \leq k \leq n} |p_k|$, index n is not fixed, is not complete. [4]
- (b) Let X be a complex Banach algebra with an identity. If $x \in X$ and $\lambda \in \mathbb{C}$ then show that the resolvent function $x(\lambda)$ is analytic at every point of $\rho(x)$, the resolvent set of x . [5]
- 7 (a) Define weak* topology for a given normed linear space. If X is a normed linear space then prove that weak* topology on X^* , the first dual of X , is Hausdorff. [2+2]
- (b) State and prove Gelfand Mazur Theorem. [5]

M.A./M.Sc. Semester IV Examination, 2019 (under DDE)

Subject: Mathematics (Pure Stream)

Paper: MPS 403 (Differential Geometry of Manifolds - II)

Time: 2 Hours

Full Marks: 45

The figures in the margin indicate full marks.

Candidates are required to give their answers in their own words as far as practicable.

[Notation and symbols have their usual meaning]

Answer any **five** questions. Only **first five** answers will be evaluated.

9×5 = 45

- 1 State and prove fundamental theorem of Riemannian geometry. [1+8]
- 2 (a) Define a gradient vector field on a Riemannian manifold. [2+3]
 If Z is a gradient vector field on a Riemannian manifold (M, g) with the Levi-Civita connection ∇ then prove that $g(\nabla_X Z, Y) = g(\nabla_Y Z, X)$ for any $X, Y \in \chi(M)$.
- (b) Let (M, g) be a Riemannian manifold and p be a point of M . Prove that the product of two symmetric endomorphism of the tangent space $T_p M$ is symmetric if and only if they commute each other. [2+2]
- 3 (a) Define almost complex manifold. [2+4]
 Show that every almost complex manifold is of even dimensional.
- (b) Show that, in an almost complex manifold M of dimension $2m$, the almost complex structure F has m eigenvalues i and m eigenvalues $-i$. [3]
- 4 (a) Define Nijenhuis tensor on an almost complex manifold. Show that it is pure in both slots. [2+3]
- (b) Obtain a necessary and sufficient condition for a vector field in an almost complex manifold to be contravariant almost analytic. [4]
- 5 (a) Deduce Gauss and Weingarten formulae for the submanifold of a Riemannian manifold. [6]
- (b) Define a manifold of constant curvature with an example. [3]
- 6 (a) Define Einstein manifold. Prove that a Riemannian manifold (M^n, g) (of dimension $n > 2$) of constant curvature is an Einstein manifold. Is the converse true? Justifying your answer. [1+3+2]
- (b) Show that the scalar curvature of an $n (> 2)$ -dimensional Einstein manifold is constant. [3]
- 7 (a) Define sectional curvature of a Riemannian manifold. [2+5]
 Prove that the curvature tensor of a Riemannian manifold (M, g) at a point p is uniquely determined by sectional curvatures of all 2-dimensional tangent subspaces of $T_p M$ at p .
- (b) State Schur's Theorem. [2]